

Metrics for Differential Privacy

Application to Location-based Systems

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joint work with

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[PETS'13], [CCS'13] and ongoing work

CAPPRIS meeting, Sep 10, 2013

Differential Privacy

- ▶ A notion of privacy from the area of **statistical databases**
- ▶ Goal: **disclose aggregate information** while protecting the **value of an individual**

Differential Privacy

Name/Id	age	weight	sex	epilepsy	...
Mario Rossi	65	82	M	yes	...
Daniele Bianchi	35	120	M	yes	...
Lucia Verdi	40	45	F	no	...
...

We want to disclose

- ▶ How many people have epilepsy?
- ▶ What is the average age and weight of men who have epilepsy?

Without revealing

- ▶ Does Daniele Bianchi have the disease?
- ▶ What is the weight of Lucia?

Differential Privacy

- ▶ **Mechanism:** add **noise** to the query result

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- ▶ ϵ -differential privacy:
adjacent databases should produce **similar results**

$K(x)$ and $K(x')$ should be similar $\forall x \sim x'$

Protect the **value of an individual**

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$$d_{\mathcal{P}}(K(x), K(x')) \leq \epsilon \quad \forall x \sim x'$$

Protect the **value of an individual**

Motivation

Broaden the scope of Differential Privacy

Can differential privacy be adapted to different **privacy requirements**?

Can we use differential privacy on secrets that are **not databases**?

Differential Privacy

- ▶ Hamming dist. $d_h(x, x')$: # of elements in which x, x' differ

$$x = \langle 32, 41, 27 \rangle$$

$$x' = \langle 21, 52, 27 \rangle$$

$$d_h(x, x') = 2$$

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- ▶ Differential privacy:

$$d_{\mathcal{P}}(K(x), K(x')) \leq \epsilon d_h(x, x') \quad \forall x, x'$$

- ▶ $\epsilon d_h(x, x')$: **distinguishability metric** between x, x'
- ▶ the **closer** two databases are,
the **more similar** the outcome should be

Differential Privacy, generalization

- ▶ Arbitrary domain of secrets \mathcal{X}
- ▶ $d_{\mathcal{X}}(x, x')$: distinguishability metric between x, x'
- ▶ Many natural choices
 - ▶ numerical distance
 - ▶ geographical distance
 - ▶ ...
- ▶ It could be scaled by some ϵ : $d_{\mathcal{X}} = \epsilon d_{\mathcal{X}'}$

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$d_{\mathcal{X}}$ -privacy

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Differential Privacy, generalization

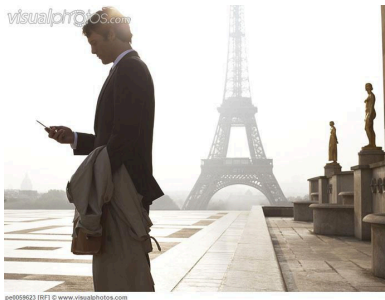
[PETS'13]

- ▶ Develop the **general theory** of d_x -privacy
 - ▶ Characterization results
 - ▶ Optimality results
- ▶ What can we **achieve** with metrics?
 - ▶ **Strengthen** differential privacy
(and get some surprising results)
 - ▶ Protect the **accuracy**, not the complete value
 - ▶ **Location** privacy

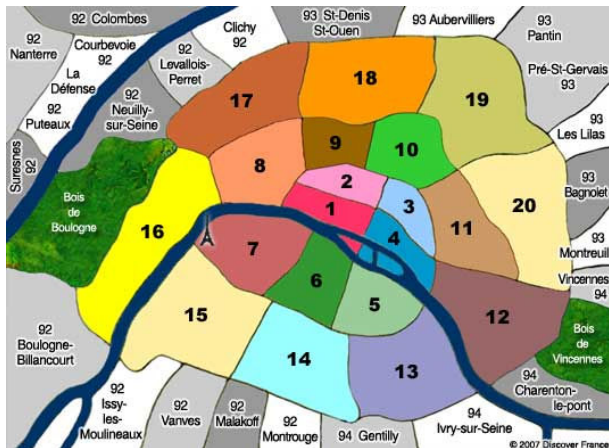
Location Based Services

Goal:

- ▶ Find a nearby restaurant, ATM, ...
- ▶ Hide the user's **location** (not identity) from the **service provider**
- ▶ the **coarse** location should be revealed, but not the **exact** one



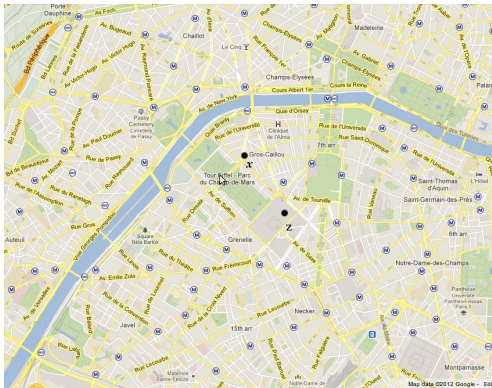
A simple cloaking “solution”



Fails when the user **moves between regions**

Obfuscation

- ▶ Add **noise** to x , report z
- ▶ Can be seen as **probabilistic** cloaking

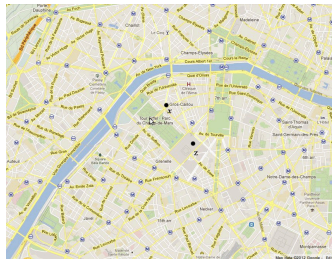


Measuring location privacy

Shokri et al, S&P'11, CCS'12

Privacy metric

Expected error of a Bayesian adversary



Construction of an **optimal mechanism**

- ▶ given a **prior** and a **utility constraint**
- ▶ find the mechanism with the **best privacy**

Drawback: depends on the **prior information** on locations

Differential privacy

adjacent databases should be indistinguishable

But we only have a single individual

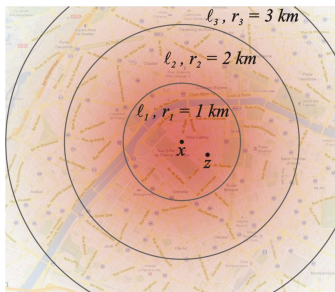
Such a mechanism would have **zero utility**

We actually **want** some locations to be distinguishable

Geo-indistinguishability [CCS'13]

the **closer** (geographically) two secrets are
the **more indistinguishable** they should be

$$d_{\mathcal{P}}(K(x), K(x')) \leq \epsilon d(x, x') \quad \forall x, x'$$



Provides privacy for **any radius r** with a **proportional level $\epsilon \cdot r$**

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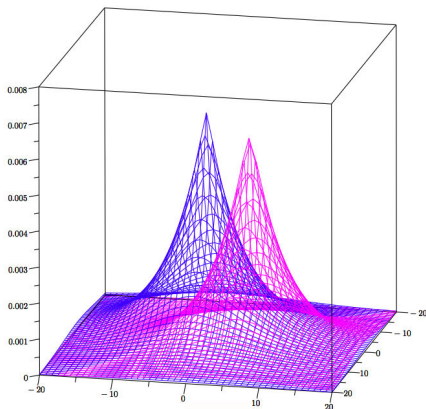
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A second characterization is obtained by comparing **prior and posterior** knowledge.

A mechanism for geo-indistinguishability

Add noise from a 2-dimensional Laplace distribution

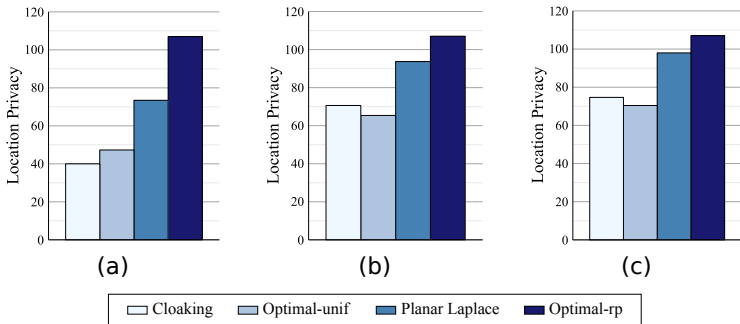


Efficient

Solve discretization and truncation issues

Comparison

- ▶ Using the privacy metric of Shokri et al
- ▶ Under various priors
- ▶ Against:
 - ▶ simple cloaking
 - ▶ optimal mechanism constructed using the correct prior
 - ▶ optimal mechanism constructed using a uniform prior

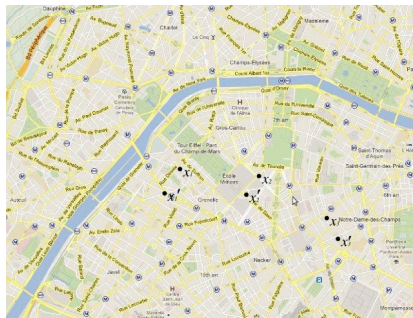


Protecting location traces

- ▶ Secrets are now tuples
 $\mathbf{x} = (x_1, \dots, x_n)$
- ▶ Distance between tuples:

$$d_{\infty}(\mathbf{x}, \mathbf{x}') = \max_i d(x_i, x'_i)$$

- ▶ Use ϵd_{∞} -privacy



Protecting location traces

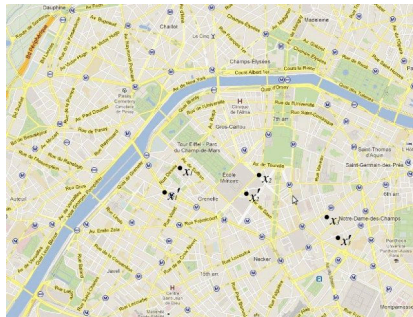
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Mechanism: add **independent noise** to each point

Problem: this only satisfies $n\epsilon$ -geo-indistinguishability

Budget: we pay ϵ each time we generate noise

Predictive mechanism

- ▶ Basic intuition: if the user is **not moving**, he should always report the **same** obfuscated location z
- ▶ An obfuscated point z_n **close** to the current location x_n can be **predicted** from the previously reported locations \mathbf{z} .

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At step n compute a prediction $z_n^* = \Omega(\mathbf{z})$

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Privacy:

- ▶ if the test is differentially private, then the mechanism satisfies geo-indistinguishability
- ▶ We pay
 - ▶ a (small) ϵ_t for each test
 - ▶ plus an ϵ each time we add noise
- ▶ If the prediction is good, the savings are big

Constructing an optimal mechanism

Shokri et al, CCS'12

- ▶ given a **prior** and a **utility constraint**
- ▶ find the mechanism with the **best privacy** (expected error)

Both privacy and utility **depend on the prior**.

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Ongoing work:

- ▶ given a **privacy constraint** (geo-indistinguishability)
- ▶ find the mechanism with the **best utility** (for a given prior)
- ▶ Advantages:
 - ▶ privacy is a **hard constraint**
 - ▶ **only utility** depends on the prior
- ▶ graph-based technique for reducing the number of constraints

Conclusion

- ▶ Metrics allow to **broaden the scope** of Differential Privacy
 - ▶ Capture **new privacy notions**
 - ▶ Extend to new applications, where **secrets are not databases**
- ▶ Natural application: **location privacy**
- ▶ Ongoing work:
 - ▶ predictive mechanism for location traces
 - ▶ construction of optimal mechanism

Questions?